

An introduction to INLA with a comparison to JAGS

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(Thanks to Håvard Rue, University of Science and Technology Trondheim, Norway)

Universitat de Girona
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The screenshot shows a Google search for 'INLA' in a browser window. The search results include:

- Irish National Liberation Army - Wikipedia, the free encyclopedia**
en.wikipedia.org/wiki/Irish_National_Liberation_Army
The **Irish National Liberation Army** (Irish: Arm Saoirse Náisiúnta na hÉireann) or **INLA** is an Irish republican socialist paramilitary group that was formed on 8 ...
[History](#) - [Deaths as a result of activity](#) - [External links](#) - [References](#)
- The R-INLA project**
www.r-inla.org/
This is the site for the **INLA** approach to Bayesian inference within the R project for Statistical Computing.
You've visited this page 2 times. Last visit: 24/03/13
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www.youtube.com/watch?v=pZ9Kkx8PmM
Aug 19, 2007 · Uploaded by discarya
I spent 1 hole year in LA when a I was 18 yrs, and just for this song I promised my self to comeback at 28 and ...
[More videos for INLA](#)
- BBC NEWS | UK | Northern Ireland | Who are the INLA?**
news.bbc.co.uk/2/hi/uk_news/northern_ireland/19801380.stm
Oct 11, 2009 - A look at the history of the Irish National Liberation Army (INLA), which is set to renounce violence and decommission its weapons.
- Images for INLA - Report images**
- Discover Los Angeles - California Travel, Vacation, and Things to Do**
www.discoverlosangeles.com/ - United States
The Valley is the largest region in **Los Angeles**, a sprawling area that is home to historic movie ... Top things to do in **LA**, suggested by the people who live here.
[dineLA](#) - [LA Tourism](#) - [Events](#) - [Meeting Professionals](#)
- Irish National Liberation Army Page - Angefire**

The screenshot shows a Google search for 'INLA' on a Windows desktop. The search results page displays several links and a large image. The top navigation bar includes 'Applications', 'Places', and 'Google Search'. The search bar contains 'INLA' and the search button is visible. Below the search bar, there are tabs for 'Web', 'Images', 'Maps', 'Shopping', 'News', and 'More'. The search results include:

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At the bottom of the page, there is a navigation bar with 'inla - Google Search' and a search button.

- ① **9.30 – 10.15: (Quick & moderately clean) introduction to Bayesian computation**
 - MCMC
 - Latent Gaussian models
 - Gaussian Markov Random Fields
- ② 10.15 – 10.30: Coffee break
- ③ 10.30 – 11.15: Introduction to INLA
 - Basic ideas
 - Some details
 - A simple example
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- ⑤ 11.30 – 12.30: Using the package R-INLA
 - How does it work?
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(Quick & moderately clean) introduction to Bayesian computation

- In a (**very** small!) nutshell, Bayesian inference boils down to the computation of **posterior** and/or **predictive** distributions

$$p(\boldsymbol{\theta} | \mathbf{y}) = \frac{p(\mathbf{y} | \boldsymbol{\theta})p(\boldsymbol{\theta})}{\int p(\mathbf{y} | \boldsymbol{\theta})p(\boldsymbol{\theta})d\boldsymbol{\theta}} \quad p(y^* | \mathbf{y}) = \int p(y^* | \boldsymbol{\theta})p(\boldsymbol{\theta} | \mathbf{y})d\boldsymbol{\theta}$$

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- Since the advent of simulation-based techniques (notably MCMC), Bayesian computation has enjoyed incredible development
- This has certainly been helped by dedicated software (eg BUGS and then WinBUGS, OpenBUGS, JAGS)
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- MCMC methods are very general and can effectively be applied to “any” model
- However:
 - Even if **in theory**, MCMC can provide (nearly) exact inference, given perfect convergence and MC error $\rightarrow 0$, in practice, this has to be balanced with model complexity and running time
 - This is particularly an issue for problems characterised by large data or very complex structure (eg hierarchical models)

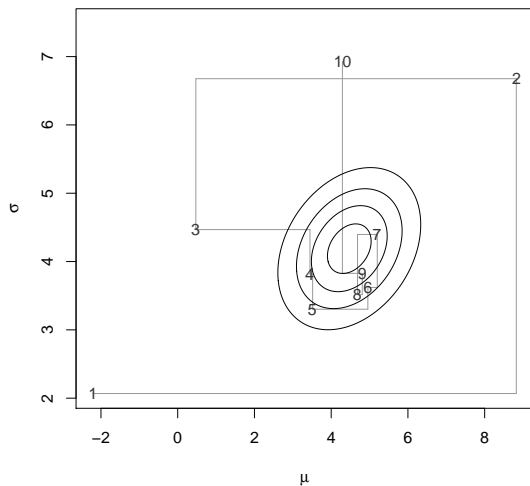
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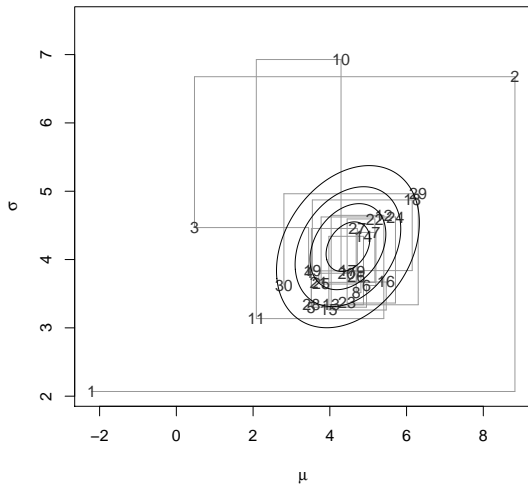
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 3. Repeat step 2. for S times until convergence is reached to the target distribution $p(\theta | y)$
 4. Use the sample from the target distribution to compute all relevant statistics: (posterior) mean, variance, credibility intervals, etc.
- If the *full conditionals* are not readily available, they need to be estimated (eg via Metropolis-Hastings or slice sampling) before applying the GS

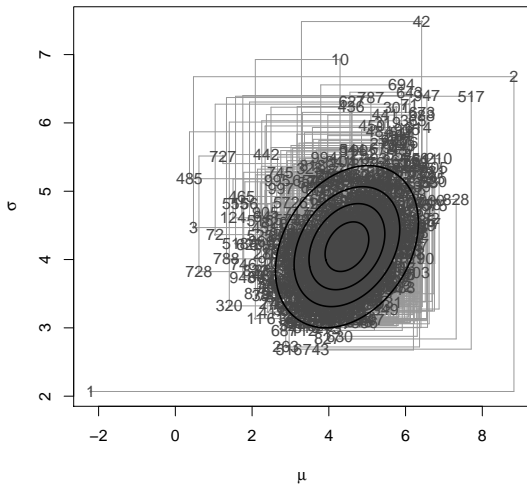
After 10 iterations

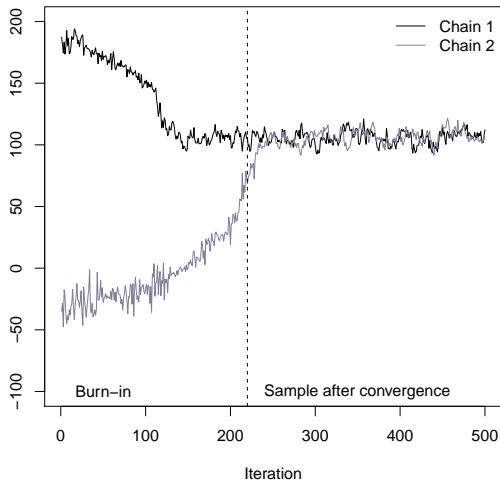


After 30 iterations

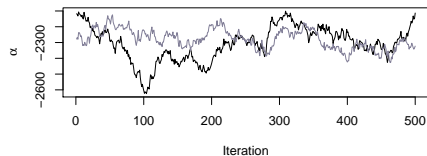


After 1000 iterations

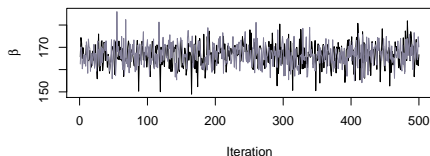
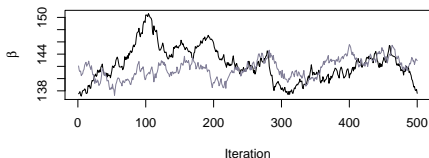
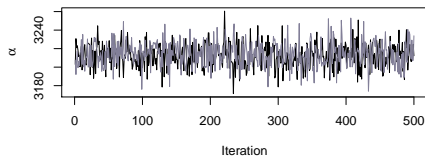




Uncentred model

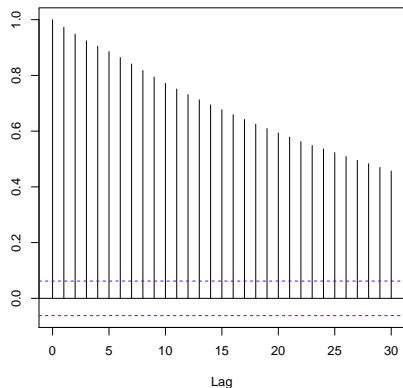
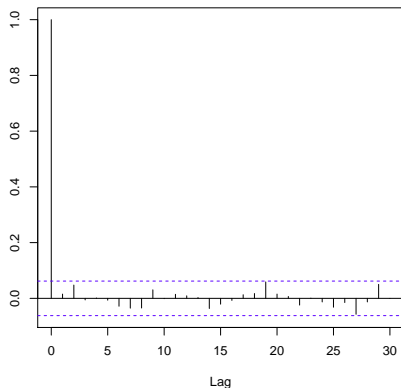


Centred model



- Formal assessment of convergence: potential scale reduction

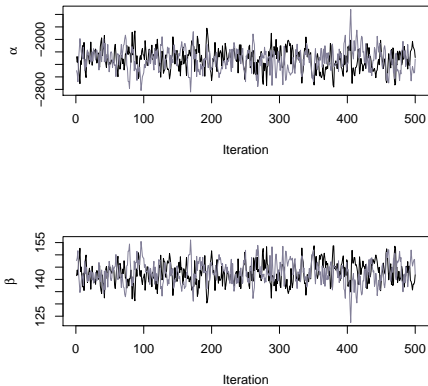
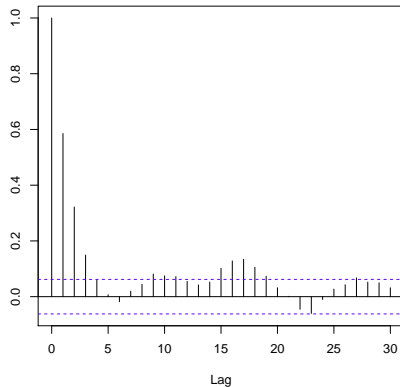
$$\hat{R} = \sqrt{\frac{\widehat{\text{Var}}(\theta_k | \mathbf{y})}{W(\theta_k)}}$$

Autocorrelation function for α – Uncentred modelAutocorrelation function for α – Centred model

- Formal assessment of autocorrelation: effective sample size

$$n_{\text{eff}} = \frac{S}{1 + 2 \sum_{t=1}^{\infty} \rho_t}$$

Uncentred model with thinning

Autocorrelation function for α – Uncentred model with thinning

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The basic ideas revolve around

- Formulating the model using a specific characterisation
 - All models that can be formulated in this way have certain features in common, which facilitate the computational aspects
 - The characterisation is still quite general and covers a wide range of possible models (more on that later!)
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- Use some basic probability conditions to approximate the relevant distributions
- Compute the relevant quantities typically using numerical methods

- The general problem of (parametric) inference is posited by assuming a probability model for the observed data, as a function of some relevant parameters

$$\mathbf{y} \mid \boldsymbol{\theta}, \boldsymbol{\psi} \sim p(\mathbf{y} \mid \boldsymbol{\theta}, \boldsymbol{\psi}) = \prod_{i=1}^n p(y_i \mid \boldsymbol{\theta}, \boldsymbol{\psi})$$

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- Often (in fact for a surprisingly large range of models!), we can assume that the parameters are described by a **Gaussian Markov Random Field** (GMRF)

$$\boldsymbol{\theta} \mid \boldsymbol{\psi} \sim \text{Normal}(\mathbf{0}, \boldsymbol{\Sigma}(\boldsymbol{\psi}))$$

$$\theta_l \perp\!\!\!\perp \theta_m \mid \boldsymbol{\theta}_{-lm}$$

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- This kind of models is often referred to as **Latent Gaussian models**

- In general, we can partition $\boldsymbol{\psi} = (\boldsymbol{\psi}_1, \boldsymbol{\psi}_2)$ and re-express a LGM as

$$\begin{aligned}\boldsymbol{\psi} &\sim p(\boldsymbol{\psi}) && \text{("hyperprior")} \\ \boldsymbol{\theta} \mid \boldsymbol{\psi} &\sim p(\boldsymbol{\theta} \mid \boldsymbol{\psi}) = \text{Normal}(0, \boldsymbol{\Sigma}(\boldsymbol{\psi}_1)) && \text{("GMRF prior")} \\ \mathbf{y} \mid \boldsymbol{\theta}, \boldsymbol{\psi} &\sim \prod_i p(y_i \mid \boldsymbol{\theta}, \boldsymbol{\psi}_2) && \text{("data model")}\end{aligned}$$

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ie ψ_1 are the **hyper-parameters** and ψ_2 are **nuisance parameters**

- The dimension of θ can be very large (eg 10^2 - 10^5)
- Conversely, because of the conditional independence properties, the dimension of ψ is generally small (eg 1-5)

- A very general way of specifying the problem is by modelling the mean for the i -th unit by means of an additive linear predictor, defined on a suitable scale (e.g. logistic for binomial data)

$$\eta_i = \alpha + \sum_{m=1}^M \beta_m x_{mi} + \sum_{l=1}^L f_l(z_{li})$$

where

- α is the intercept;
- $\boldsymbol{\beta} = (\beta_1, \dots, \beta_M)$ quantify the effect of $\boldsymbol{x} = (x_1, \dots, x_M)$ on the response;
- $\boldsymbol{f} = \{f_1(\cdot), \dots, f_L(\cdot)\}$ is a set of functions defined in terms of some covariates $\boldsymbol{z} = (z_1, \dots, z_L)$

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- **NB:** This of course implies some form of Normally-distributed marginals for $\alpha, \boldsymbol{\beta}$ and \boldsymbol{f}

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- Spatial and spatio-temporal models
 - Two components: $f_1(\cdot) \sim \text{CAR}$ (Spatially structured effects)
 - $f_2(\cdot) \sim \text{Normal}(0, \sigma_{f_2}^2)$ (Unstructured residual)

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 - $f_l(\cdot) \sim \text{AR}(\phi, \sigma_\varepsilon^2)$
- Survival models / logGaussian Cox Processes
 - More complex specification in theory, but relatively easy to fit within the INLA framework!

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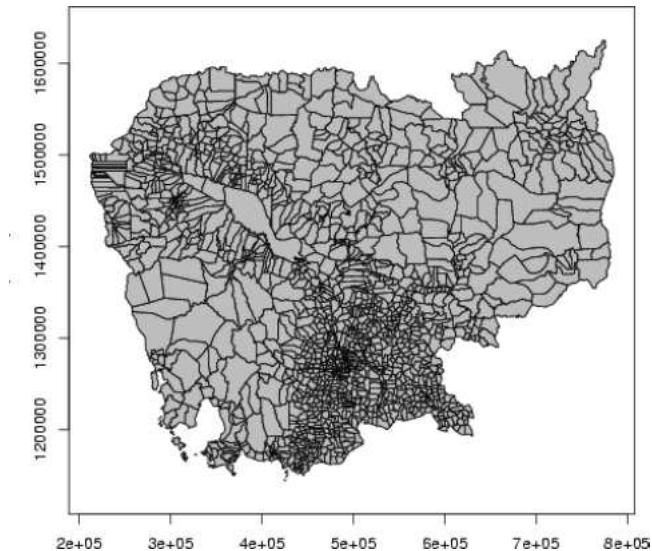
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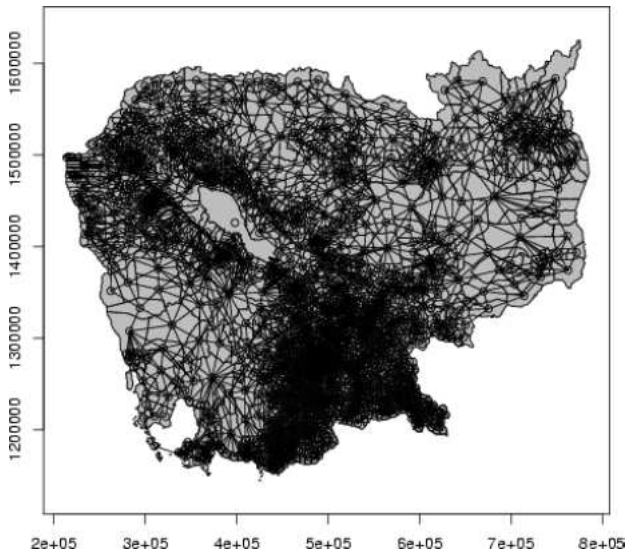
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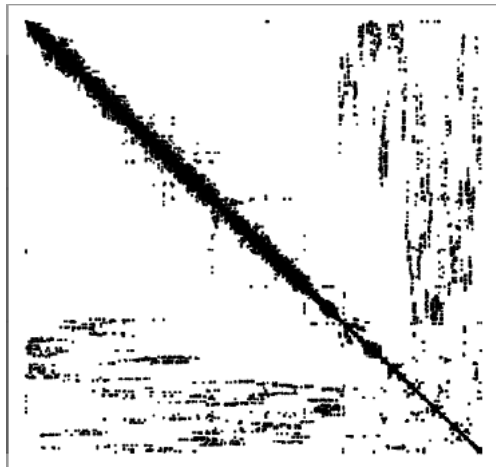
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 - If it happens to be sparse, this implies (marginal) independence among the relevant elements of θ — this is generally too stringent a requirement!
- Conversely, it is much simpler when using the precision matrix $Q =: \Sigma^{-1}$
 - As it turns out, it can be shown that

$$\theta_l \perp\!\!\!\perp \theta_m \mid \theta_{-lm} \Leftrightarrow Q_{lm} = 0$$

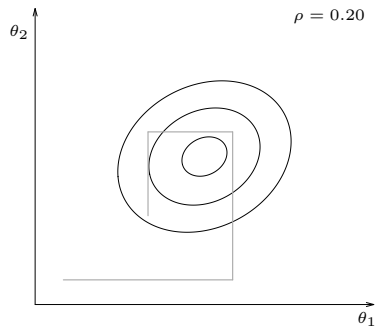
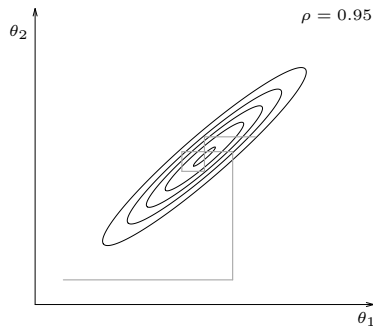
- Thus, under **conditional** independence (which is a less restrictive constraint), the precision matrix is typically **sparse**
- We can use existing numerical methods to deal with sparse matrices (eg the R package **Matrix**)
- Most computations in GMRFs are performed in terms of computing Cholesky's factorisations



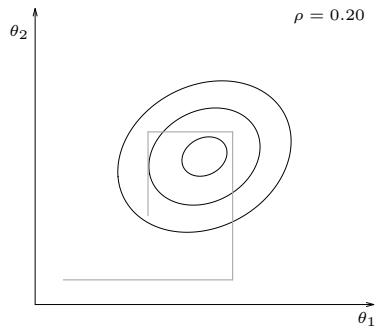
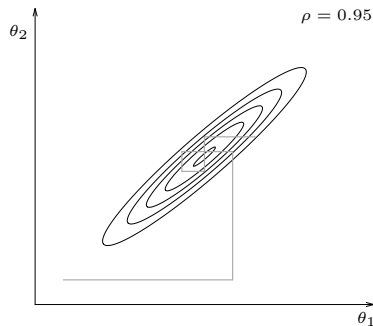




- (Standard) MCMC methods tend to perform poorly when applied to (non-trivial) LGMs. This is due to several factors
 - The components of the latent Gaussian field θ tend to be highly correlated, thus impacting on convergence and autocorrelation
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- Again, blocking and overparameterisation can **alleviate**, but rarely eliminate the problem

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 - Issues with convergence
 - Time to run can be very long
- A wide class of statistical models can be represented in terms of LGM
- This allows us to take advantage of nice computational properties
 - GMRFs
 - Sparse precision matrices
- This is at the heart of the INLA approach

Introduction to INLA

- The starting point to understand the INLA approach is the definition of conditional probability, which holds for any pair of variables (x, z) — and, technically, provided $p(z) > 0$

$$p(x | z) =: \frac{p(x, z)}{p(z)}$$

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- In particular, a conditional version can be obtained further considering a third variable w as

$$p(z | w) = \frac{p(x, z | w)}{p(x | z, w)}$$

which is particularly relevant to the Bayesian case

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- Setting $\hat{\sigma}^2 = -1 / \frac{\partial^2 \log g(\hat{x})}{\partial x^2}$ we can re-write

$$\log g(x) \approx \log g(\hat{x}) - \frac{1}{2\hat{\sigma}^2} (x - \hat{x})^2$$

or equivalently

$$\int g(x) dx = \int e^{\log g(x)} dx \approx \text{const} \int \exp \left[-\frac{(x - \hat{x})^2}{2\hat{\sigma}^2} \right] dx$$

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- Thus, under LA, $g(x) \approx \text{Normal}(\hat{x}, \hat{\sigma}^2)$

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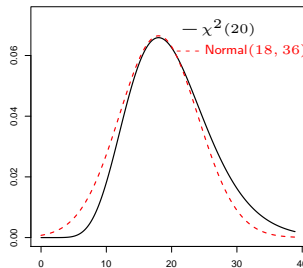
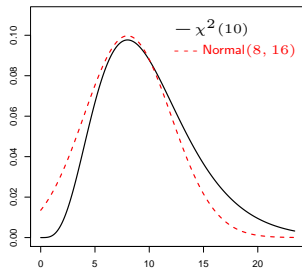
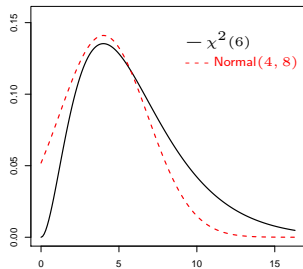
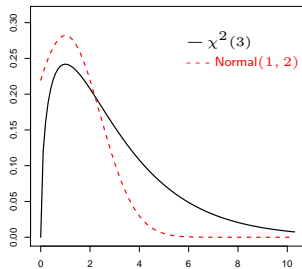
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- Consequently, we can approximate $p(x)$ as

$$p(x) \approx \tilde{p}(x) = \text{Normal}(k - 2, 2(k - 2))$$



- The general idea is that using the fundamental probability equations, we can approximate a generic conditional (posterior) distribution as

$$\tilde{p}(z | w) = \frac{p(x, z | w)}{\tilde{p}(x | z, w)},$$

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- This idea can be used to approximate any generic required posterior distribution

Objective of Bayesian estimation

- In a Bayesian LGM, the required distributions are

$$p(\theta_j | \mathbf{y}) = \int p(\theta_j, \boldsymbol{\psi} | \mathbf{y}) d\boldsymbol{\psi} = \int p(\boldsymbol{\psi} | \mathbf{y}) p(\theta_j | \boldsymbol{\psi}, \mathbf{y}) d\boldsymbol{\psi}$$
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 - $p(\theta_j | \boldsymbol{\psi}, \mathbf{y})$, which is needed to compute the marginal posterior for the parameters

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where

- $\tilde{p}(\boldsymbol{\theta} \mid \boldsymbol{\psi}, \mathbf{y})$ is the Laplace approximation of $p(\boldsymbol{\theta} \mid \boldsymbol{\psi}, \mathbf{y})$
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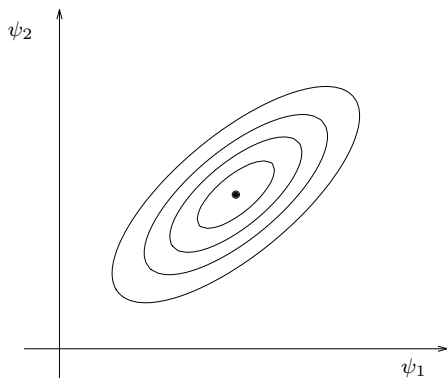
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- This is the algorithm implemented by default by R-INLA, but this choice can be modified
 - If extra precision is required, it is possible to run the full Laplace approximation — of course at the expense of running time!

Operationally, the INLA algorithm proceeds with the following steps:

- i. Explore the marginal joint posterior for the hyper-parameters $\tilde{p}(\boldsymbol{\psi} | \boldsymbol{y})$

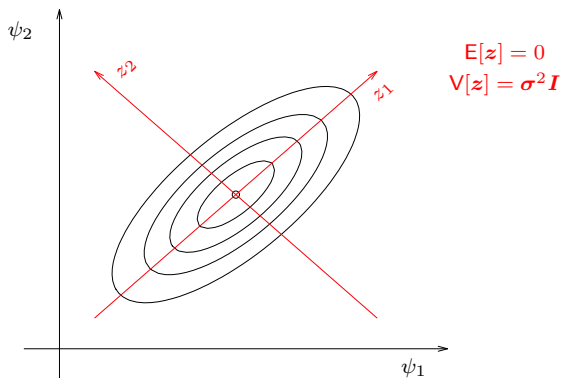
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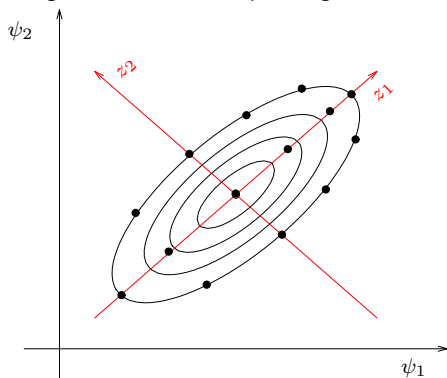
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 - Explore $\log \tilde{p}(\boldsymbol{\psi} \mid \mathbf{y})$ and produce a grid of H points $\{\boldsymbol{\psi}_h^*\}$ associated with the bulk of the mass, together with a corresponding set of area weights $\{\Delta_h\}$



- ii. For each element ψ_h^* in the grid,
- Obtain the marginal posterior $\tilde{p}(\psi_h^* | \mathbf{y})$, using interpolation and possibly correcting for (probable) skewness by using log-splines;
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 - Evaluate the conditional posteriors $\tilde{p}(\theta_j | \psi_h^*, \mathbf{y})$ on a grid of selected values for θ_j ;
- iii. Marginalise ψ_h^* to obtain the marginal posteriors $\tilde{p}(\theta_j | \mathbf{y})$ using **numerical integration**

$$\tilde{p}(\theta_j | \mathbf{y}) \approx \sum_{h=1}^H \tilde{p}(\theta_j | \psi_h^*, \mathbf{y}) \tilde{p}(\psi_h^* | \mathbf{y}) \Delta_h$$

So, it's all in the name...

Integrated Nested Laplace Approximation

- Because Laplace approximation is the basis to estimate the unknown distributions
- Because the Laplace approximations are nested within one another
 - Since (2.) is needed to estimate (1.)
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- Suppose we want to make inference on a very simple model

$$\begin{aligned}y_i | \theta, \psi &\sim \text{Normal}(\theta, \psi) && (\psi = \sigma^{-2} \text{ is the precision}) \\ \theta | \psi &\sim \text{Normal}(\theta_0, \psi_0) && (\theta_0, \psi_0 \text{ known}) \\ \psi &\sim \text{Gamma}(a_0, b_0) && (a_0, b_0 \text{ known})\end{aligned}$$

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- **NB:** This model is in fact semi-conjugated, (θ, ψ) are *a priori* independent and so inference is possible numerically or using simple MCMC algorithms

$$\begin{aligned}
 - \theta \mid \mathbf{y}, \psi &\sim \text{Normal}(\theta_n, \psi_n), \text{ with } \theta_n = \frac{\psi \sum_{i=1}^n y_i + \psi_0 \theta_0}{n\psi + \psi_0} \text{ and } \psi_n = n\psi + \psi_0 \\
 - \psi \mid \theta, \mathbf{y} &\sim \text{Gamma}(a_n, b_n), \text{ with } a_n = a_0 + \frac{n}{2} \text{ and } b_n = b_0 + \frac{\sum_{i=1}^n (y_i - \theta)^2}{2}
 \end{aligned}$$

- More generally, because of semi-conjugacy, we know that

$$\theta, \mathbf{y} \mid \psi \sim \text{Normal}(\cdot, \cdot) \quad \text{and} \quad \theta \mid \mathbf{y}, \psi \sim \text{Normal}(\cdot, \cdot)$$

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- Thus

$$\begin{aligned} p(\psi \mid \mathbf{y}) &\propto p(\mathbf{y} \mid \psi)p(\psi) \\ &\propto \frac{\overbrace{p(\theta, \mathbf{y} \mid \psi)}^{\text{Gaussian}} p(\psi)}{\underbrace{p(\theta \mid \mathbf{y}, \psi)}_{\text{Gaussian}}} \end{aligned}$$

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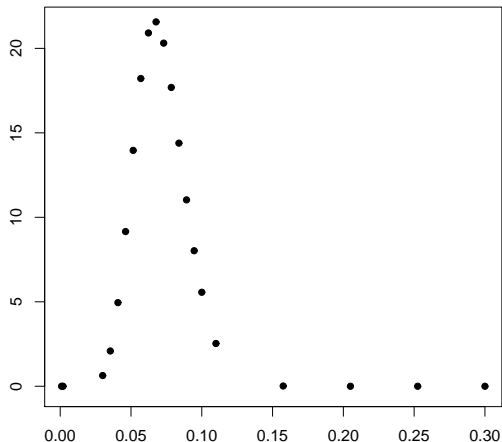
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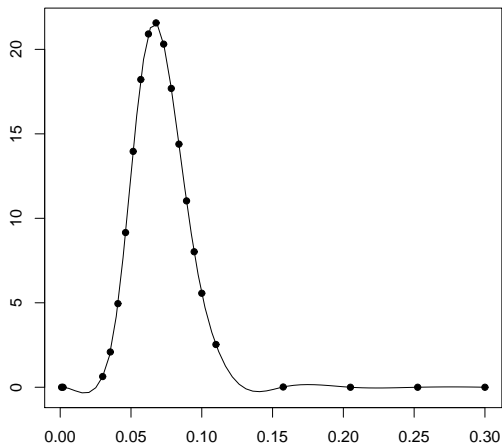
$$p(\theta \mid \mathbf{y}) = \int \underbrace{p(\theta \mid \mathbf{y}, \psi)}_{\text{Gaussian}} \underbrace{p(\psi \mid \mathbf{y})}_{\text{Approximated}} d\psi$$

1. Select a grid of H points for ψ ($\{\psi_h^*\}$) and the associated area weights ($\{\Delta_h\}$)

Posterior marginal for ψ : $p(\psi | \mathbf{y}) \propto \frac{p(\theta, \mathbf{y} | \psi) p(\psi)}{p(\theta | \mathbf{y}, \psi)}$

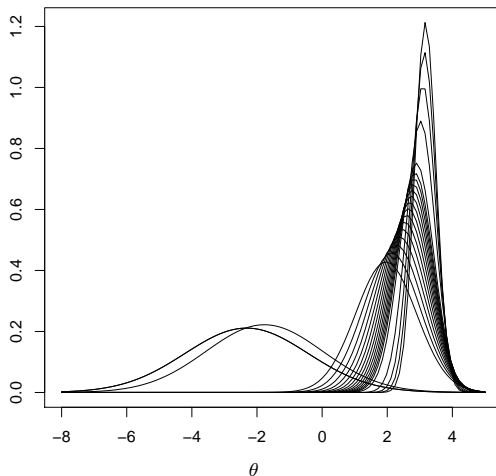


- Interpolate the posterior density to compute the approximation to the posterior

Posterior marginal for ψ (interpolated)

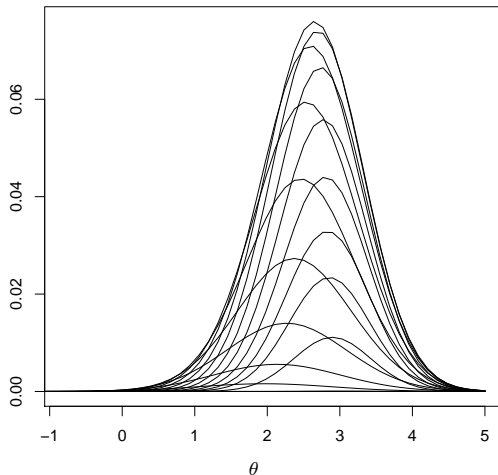
3. Approximates the conditional posterior of θ , given ψ, \mathbf{y} on the H -dimensional grid

Posterior marginal for θ , conditional on each $\{\psi_h^*\}$ value (unweighted)



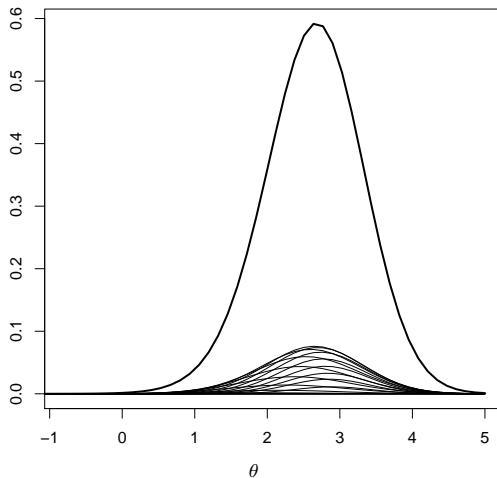
4. Weight the resulting (conditional) marginal posteriors by the density associated with each ψ on the grid

Posterior marginal for θ , conditional on each $\{\psi_h^*\}$ value (weighted)



5. (Numerically) sum over all the conditional densities to obtain the marginal posterior for θ

Posterior marginal for $\theta : p(\theta | \mathbf{y})$



- The basic idea behind the INLA procedure is simple
 - Repeatedly use Laplace approximation and take advantage of computational simplifications due to the structure of the model
 - Use numerical integration to compute the required posterior marginal distributions
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 - (If necessary) refine the estimation (eg using a finer grid)
- Complications are mostly computational and occur when
 - Extending to more than one hyper-parameter
 - Markedly non-Gaussian observations

Using the package R-INLA

Good news is that all the procedures needed to perform INLA are implemented in a R package. This is effectively made by two components

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① The **GMRFLib** library

- This is a C library for fast and exact simulation of GMRFs, used to perform
 - Unconditional simulation of a GMRF;
 - Various types of conditional simulation from a GMRF;
 - Evaluation of the corresponding log-density;
 - Generation of blockupdates in MCMC-algorithms using GMRF-approximations or auxiliary variables, construction of non-Gaussian approximations to hidden GMRFs, approximate inference using INLA

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NB: Because the package R-INLA relies on a standalone C program, it is not available directly from CRAN

- Visit the website

www.r-inla.org

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source("http://www.math.ntnu.no/inla/givemeINLA.R")
```
- Later, you can upgrade the package by typing

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inla.upgrade()
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- A test-version (which may contain unstable updates/new functions) can be obtained by typing

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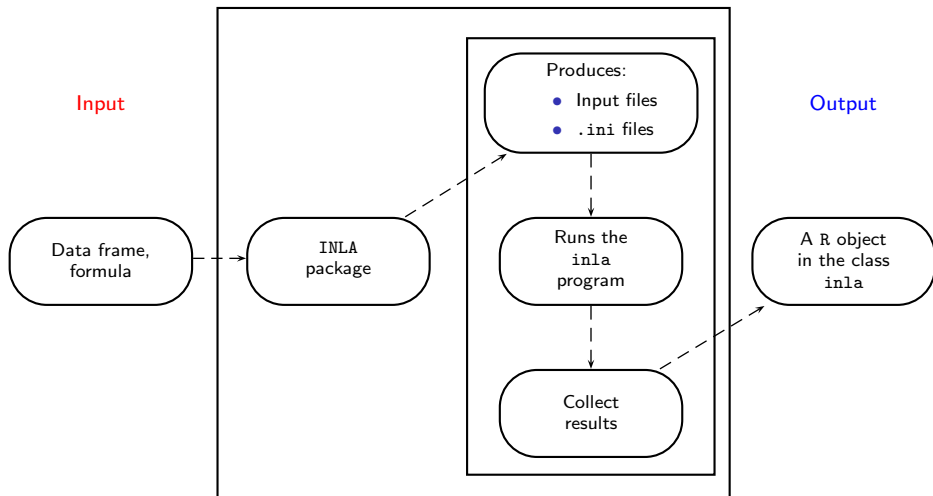
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- R-INLA runs natively under Linux, Windows and Mac and it is possible to do multi-threading using OpenMP



- There has been a great effort lately in producing quite a lot of user-friendly(-ish) documentation
- Tutorials are (or will shortly be) available on
 - Basic INLA (probably later this year)
 - SPDE (spatial models based on stochastic partial differential equations) models
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- Blangiardo & Cameletti *Spatial and spatio-temporal Bayesian models with R-INLA* (out end of 2014)
- Much of the recent development in R-INLA is devoted to extending the applications of INLA for spatial and spatio-temporal models as well as producing detailed information
- The website also has a discussion forum and a FAQ page

1. The first thing to do is to **specify the model**

- For example, assume we have a generic model

$$\begin{aligned}
 y_i &\stackrel{iid}{\sim} p(y_i | \theta_i) \\
 \eta_i &= g(\theta_i) = \beta_0 + \beta_1 x_{1i} + \beta_2 x_{2i} + f(z_i)
 \end{aligned}$$

where

- $\mathbf{x} = (x_1, x_2)$ are observed covariates for which we are assuming a linear effect on some function $g(\cdot)$ of the parameter θ_i
- $\boldsymbol{\beta} = (\beta_0, \beta_1, \beta_2) \sim \text{Normal}(0, \tau_1^{-1})$ are unstructured (“fixed”) effects
- z is an **index**. This can be used to include structured (“random”), spatial, spatio-temporal effect, etc.
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 - $f \sim \text{Normal}(0, \mathbf{Q}_f^{-1}(\tau_2))$ is a suitable function used to model the structured effects
- As mentioned earlier, this formulation can actually be used to represent quite a wide class of models!

- The model is translated in R code using a **formula**
- This is sort of standard in R (you would do pretty much the same for calls to functions such as `lm`, or `glm`, or `lmer`)

```
formula = y ~ x1 + x2 + f(z, model=...)
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- The `f()` function can account for several structured effects
- This is done by specifying a different `model`
 - `iid`, `iid1d`, `iid2d`, `iid3d` specify random effects
 - `rw1`, `rw2`, `ar1` are smooth effect of covariates or time effects
 - `seasonal` specifies a seasonal effect
 - `besag` models spatially structured effects (CAR)
 - `generic` is a user-defined precision matrix

2. Call the function `inla`, specifying the data and options (more on this later),
eg

```
m = inla(formula, data=data.frame(y,x1,x2,z))
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- The data need to be included in a suitable `data.frame`
- R returns an object `m` in the class `inla`, which has some methods available
 - `summary()`
 - `plot()`
- The options let you specify the priors and hyperpriors, together with additional output


```
names(m)
```

```
[1] "names.fixed"           "summary.fixed"
[3] "marginals.fixed"      "summary.lincomb"
[5] "marginals.lincomb"    "size.lincomb"
[7] "summary.lincomb.derived" "marginals.lincomb.derived"
[9] "size.lincomb.derived" "mlik"
[11] "cpo"                   "model.random"
[13] "summary.random"       "marginals.random"
[15] "size.random"          "summary.linear.predictor"
[17] "marginals.linear.predictor" "summary.fitted.values"
[19] "marginals.fitted.values" "size.linear.predictor"
[21] "summary.hyperpar"     "marginals.hyperpar"
[23] "internal.summary.hyperpar" "internal.marginals.hyperpar"
[25] "si"                   "offset.linear.predictor"
[27] "model.spde2.blc"     "summary.spde2.blc"
[29] "marginals.spde2.blc" "size.spde2.blc"
[31] "logfile"             "misc"
[33] "dic"                 "mode"
[35] "neffp"               "joint.hyper"
[37] "nhyper"              "version"
[39] "Q"                   "graph"
[41] "cpu.used"            ".args"
[43] "call"                "model.matrix"
```

First, generate some data from an assumed model

$$y_i \sim \text{Binomial}(\pi_i, N_i), \quad \text{for } i = 1, \dots, n = 12$$

```
library(INLA)

# Data generation
n=12
Ntrials = sample(c(80:100), size=n, replace=TRUE)
eta = rnorm(n,0,0.5)
prob = exp(eta)/(1 + exp(eta))
y = rbinom(n, size=Ntrials, prob = prob)
data=data.frame(y=y,z=1:n,Ntrials)
```

data

	y	z	Ntrials
1	50	1	95
2	37	2	97
3	36	3	93
4	47	4	96
5	39	5	80
6	67	6	97
7	60	7	89
8	57	8	84
9	34	9	89
10	57	10	96
11	46	11	87
12	48	12	98

We want to fit the following model

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 \alpha &\sim \text{Normal}(0, 1000) && \text{("fixed" effect)} \\
 f(z_i) &\sim \text{Normal}(0, \sigma^2) && \text{("random" effect)} \\
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This can be done by typing in R

```

formula = y ~ f(z,model="iid",
               hyper=list(list(prior="flat")))
m=inla(formula, data=data,
        family="binomial",
        Ntrials=Ntrials,
        control.predictor = list(compute = TRUE))
summary(m)
    
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Call:
c("inla(formula = formula, family = \"binomial\", data = data, Ntrials = Ntrials,
  \"control.predictor = list(compute = TRUE)\"))
```

Time used:

Pre-processing	Running inla	Post-processing	Total
0.2258	0.0263	0.0744	0.3264

Fixed effects:

	mean	sd	0.025quant	0.5quant	0.975quant	kld
(Intercept)	-0.0021	0.136	-0.272	-0.0021	0.268	0

Random effects:

Name	Model
z	IID model

Model hyperparameters:

	mean	sd	0.025quant	0.5quant	0.975quant
Precision for z	7.130	4.087	2.168	6.186	17.599

Expected number of effective parameters(std dev): 9.494(0.7925)

Number of equivalent replicates : 1.264

Marginal Likelihood: -54.28

CPO and PIT are computed

Posterior marginals for linear predictor and fitted values computed

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- For each unstructured (“fixed”) effect, R-INLA reports a set of summary statistics from the posterior distribution
- The value of the Kullback-Leibler divergence (KLD) describes the difference between the standard Gaussian and the Simplified Laplace Approximation to the marginal posterior densities
 - Small values indicate that the posterior distribution is well approximated by a Normal distribution
 - If so, the more sophisticated SLA gives a “good” error rate and therefore there is no need to use the more computationally intensive “full” Laplace approximation

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```
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- Also for each hyper-parameter, the summary statistics are reported to describe the posterior distribution
- **NB:** INLA reports results on the **precision** scale (more on this later)

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- The number of equivalent replicates indicates the available information (in terms of sample size) per effective parameter
 - Example: there are 12 data points and on average 9.5 parameters; so each is estimated using on average $12/9.5 \approx 1.3$ data points
 - Low values (with respect to the overall sample size) are indicative of poor fit

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CPO and PIT are computed

- R-INLA can produce two types of “leave-one-out” measures of fit
 - ① Conditional Predictive Ordinate (CPO): $p(y_i | \mathbf{y}_{-i})$
 - “Extreme” values for CPO indicate a surprising observation
 - ② Probability Integral Transforms (PIT): $\Pr(y_i^{\text{new}} \leq y_i | \mathbf{y}_{-i})$
 - “Extreme” values for PIT indicate outliers
 - A histogram of PIT that does not look Uniformly distributed indicate lack of fit for the current model

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 - “Extreme” values for CPO indicate a surprising observation
 - ② Probability Integral Transforms (PIT): $\Pr(y_i^{\text{new}} \leq y_i | \mathbf{y}_{-i})$
 - “Extreme” values for PIT indicate outliers
 - A histogram of PIT that does not look Uniformly distributed indicate lack of fit for the current model

- If the option

```
control.compute=list(cpo=TRUE)
```

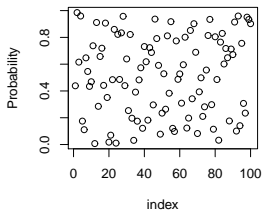
is added to the call to the function `inla` then the resulting object contains values for CPO and PIT, which can then be post-processed

- **NB:** for the sake of model checking, it is useful to to increase the accuracy of the estimation for the tails of the marginal distributions
- This can be done by adding the option

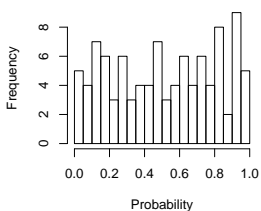
```
control.inla = list(strategy = "laplace", npoints = 21)
```

to add more evaluation points (`npoints=21`) instead of the default `npoints=9`

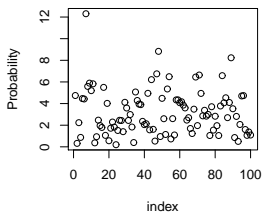
The PIT-values, n.fail0



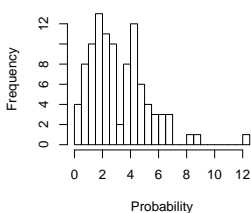
The PIT-values, n.fail0



The CPO-values, n.fail0



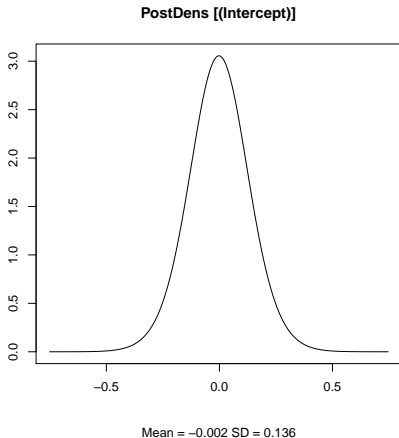
Histogram of the CPO-values, n.fail



```
plot(m)
```

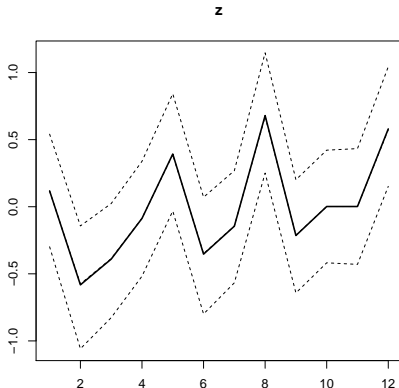
```
plot(m,
      plot.fixed.effects = TRUE,
      plot.lincomb = FALSE,
      plot.random.effects = FALSE,
      plot.hyperparameters = FALSE,
      plot.predictor = FALSE,
      plot.q = FALSE,
      plot.cpo = FALSE
    )
```

```
plot(m, single = TRUE)
```



```
plot(m)
```

```
plot(m,
      plot.fixed.effects = FALSE,
      plot.lincomb = FALSE,
      plot.random.effects = TRUE,
      plot.hyperparameters = FALSE,
      plot.predictor = FALSE,
      plot.q = FALSE,
      plot.cpo = FALSE
)
```



PostMean 0.025% 0.5% 0.975%

- The elements of the object `m` can be used for post-processing

```
m$summary.fixed
```

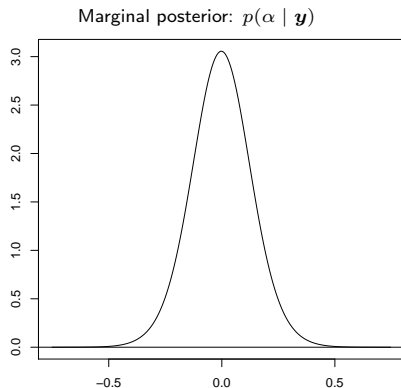
	mean	sd	0.025quant	0.5quant	0.975quant	kld
(Intercept)	-0.002092578	0.1360447	-0.2720331	-0.002101465	0.2680023	1.866805e-08

```
m$summary.random
```

```
$z
```

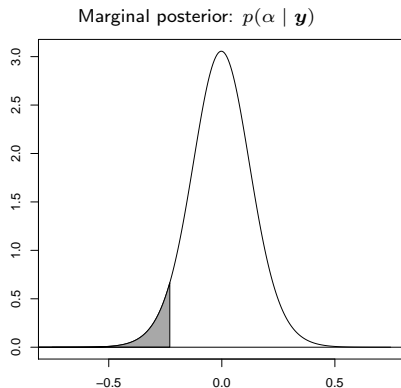
	ID	mean	sd	0.025quant	0.5quant	0.975quant	kld
1	1	0.117716597	0.2130482	-0.29854459	0.116540837	0.54071007	1.561929e-06
2	2	-0.582142549	0.2328381	-1.05855344	-0.575397613	-0.14298960	3.040586e-05
3	3	-0.390419424	0.2159667	-0.82665552	-0.386498698	0.02359256	1.517773e-05
4	4	-0.087199172	0.2174477	-0.51798771	-0.086259111	0.33838724	7.076793e-07
5	5	0.392724605	0.2220260	-0.03217954	0.388462164	0.84160800	1.604348e-05
6	6	-0.353323459	0.2210244	-0.79933142	-0.349483252	0.07088015	1.242953e-05
7	7	-0.145238917	0.2122322	-0.56726042	-0.143798605	0.26859415	2.047815e-06
8	8	0.679294456	0.2279863	0.25076022	0.672226639	1.14699903	4.145645e-05
9	9	-0.214441626	0.2141299	-0.64230245	-0.212274011	0.20094086	4.577080e-06
10	10	0.001634115	0.2131451	-0.41797579	0.001622300	0.42152562	4.356243e-09
11	11	0.001593724	0.2190372	-0.42961274	0.001581019	0.43309253	3.843622e-09
12	12	0.580008923	0.2267330	0.15173745	0.573769187	1.04330359	3.191737e-05

```
alpha <- m$marginals.fixed[[1]]  
plot(inla.sMarginal(alpha),t="1")
```



```
alpha <- m$marginals.fixed[[1]]  
plot(inla.smarginal(alpha),t="1")
```

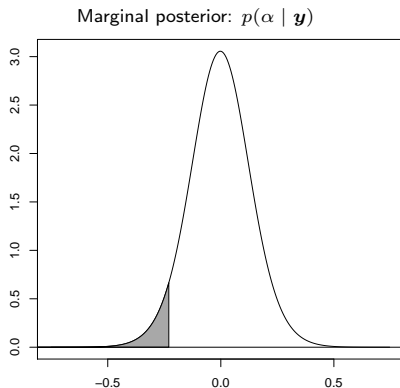
```
inla.qmarginal(0.05,alpha)  
[1] -0.2257259
```



```
alpha <- m$marginals.fixed[[1]]  
plot(inla.smarginal(alpha),t="l")
```

```
inla.qmarginal(0.05,alpha)  
[1] -0.2257259
```

```
inla.pmarginal(-.2257259,alpha)  
[1] 0.04999996
```

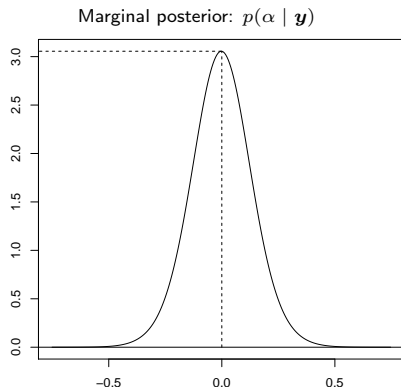


```
alpha <- m$marginals.fixed[[1]]
plot(inla.smarginal(alpha),t="l")
```

```
inla.qmarginal(0.05,alpha)
[1] -0.2257259
```

```
inla.pmarginal(-.2257259,alpha)
[1] 0.04999996
```

```
inla.dmarginal(0,alpha)
[1] 3.055793
```




```
alpha <- m$marginals.fixed[[1]]  
plot(inla.smarginal(alpha),t="1")
```

```
inla.qmarginal(0.05,alpha)  
[1] -0.2257259
```

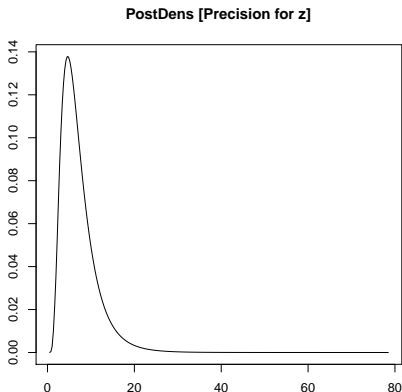
```
inla.pmarginal(-.2257259,alpha)  
[1] 0.04999996
```

```
inla.dmarginal(0,alpha)  
[1] 3.055793
```

```
inla.rmarginal(4,alpha)  
[1] 0.05307452 0.07866796 -0.09931744 -0.02027463
```

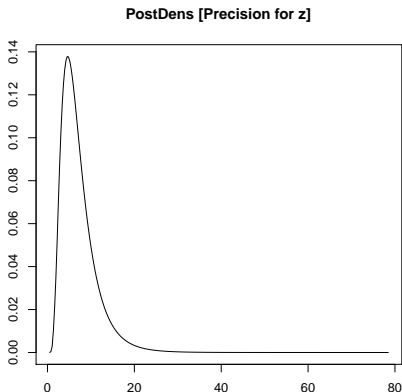
NB: INLA works by default with **precisions**

```
plot(m,  
      plot.fixed.effects = FALSE,  
      plot.lincomb = FALSE,  
      plot.random.effects = FALSE,  
      plot.hyperparameters = TRUE,  
      plot.predictor = FALSE,  
      plot.q = FALSE,  
      plot.cpo = FALSE  
)
```



NB: INLA works by default with **precisions**

```
plot(m,  
      plot.fixed.effects = FALSE,  
      plot.lincomb = FALSE,  
      plot.random.effects = FALSE,  
      plot.hyperparameters = TRUE,  
      plot.predictor = FALSE,  
      plot.q = FALSE,  
      plot.cpo = FALSE  
)
```



Problem: usually, we want to make inference on more interpretable parameters, eg **standard deviations**

- Using some built-in INLA functions

- `model$marginals.hyperpar`
- `inla.expectation`
- `inla.rmarginal`

it is possible to compute the structured variability, for example on the standard deviation scale, based on `nsamples` (default=1000) MC simulations from the estimated precision

```
s <- inla.contrib.sd(m, nsamples=1000)
s$hyper
```

```
          mean          sd      2.5%      97.5%
sd for z 0.416862 0.1098968 0.2332496 0.6478648
```

- Using some built-in INLA functions

- `model$marginals.hyperpar`
- `inla.expectation`
- `inla.rmarginal`

it is possible to compute the structured variability, for example on the standard deviation scale, based on `nsamples` (default=1000) MC simulations from the estimated precision

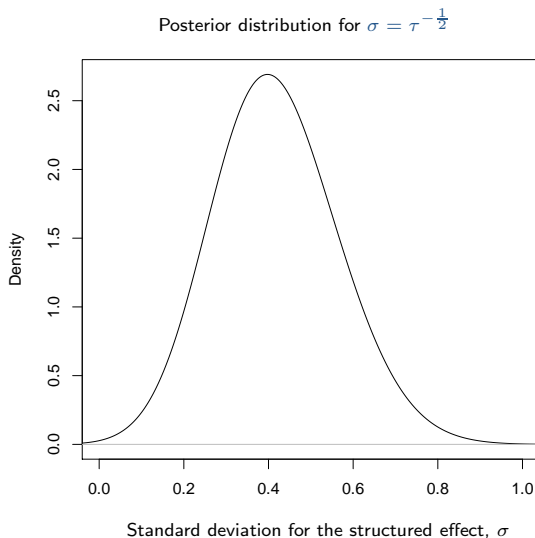
```
s <- inla.contrib.sd(m,nsamples=1000)
s$hyper
```

```

              mean          sd      2.5%      97.5%
sd for z 0.416862 0.1098968 0.2332496 0.6478648
```

- The object `s` contains a vector of simulations from the induced posterior distribution for the standard deviation scale, than can then be used for plots

```
hist(s$samples)
plot(density(s$samples,bw=.1),xlab="sigma",main="")
```



If we wanted to perform MCMC on this model, we could

- 1 Program it in JAGS/BUGS and save it as `model.txt`

```
model {
  for (i in 1:n) {
    y[i] ~ dbinom(pi[i],Ntrials[i])
    logit(pi[i]) <- alpha+f[i]
    f[i] ~ dnorm(0,tau)
  }
  alpha ~ dnorm(0,.001)
  log.sigma ~ dunif(0,10000)
  sigma <- exp(log.sigma)
  tau <- pow(sigma,-2)
}
```

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```
model {
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  }
  alpha ~ dnorm(0,.001)
  log.sigma ~ dunif(0,10000)
  sigma <- exp(log.sigma)
  tau <- pow(sigma,-2)
}
```

- 2 In R, use the library `R2jags` (or `R2WinBUGS`) to interface with the MCMC software

```
library(R2jags)
filein <- "model.txt"
dataJags <- list(y=y,n=n,Ntrials=Ntrials,prec=prec)
params <- c("sigma","tau","f","pi","alpha")
inits <- function(){ list(log.sigma=runif(1),alpha=rnorm(1),f=rnorm(n,0,1)) }
n.iter <- 100000
n.burnin <- 9500
n.thin <- floor((n.iter-n.burnin)/500)
mj <- jags(dataJags, inits, params, model.file=filein,n.chains=2, n.iter, n.burnin,
  n.thin, DIC=TRUE, working.directory=working.dir, progress.bar="text")
print(mj,digits=3,intervals=c(0.025, 0.975))
```



```
Inference for Bugs model at "model.txt", fit using jags,
 2 chains, each with 1e+05 iterations (first 9500 discarded), n.thin = 181
 n.sims = 1000 iterations saved                (Time to run: 4.918 sec)
```

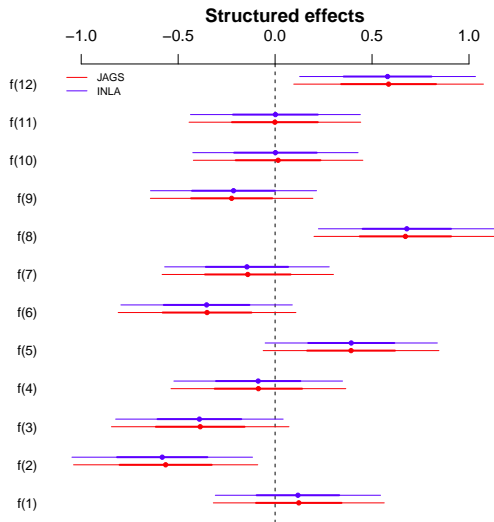
	mu.vect	sd.vect	2.5%	97.5%	Rhat	n.eff
alpha	-0.005	0.146	-0.270	0.292	1.001	1000
f[1]	0.122	0.220	-0.347	0.582	1.001	1000
f[2]	-0.564	0.238	-1.051	-0.115	1.008	190
f[3]	-0.386	0.229	-0.880	0.050	1.000	1000
f[4]	-0.086	0.225	-0.549	0.367	1.002	780
f[5]	0.392	0.227	-0.047	0.828	1.002	870
f[6]	-0.351	0.229	-0.805	0.081	1.000	1000
f[7]	-0.141	0.221	-0.578	0.286	1.001	1000
f[8]	0.672	0.236	0.246	1.200	1.002	860
f[9]	-0.224	0.210	-0.643	0.178	1.000	1000
f[10]	0.016	0.219	-0.396	0.463	1.006	1000
f[11]	-0.001	0.221	-0.441	0.416	1.002	780
f[12]	0.585	0.245	0.153	1.093	1.001	1000
sigma	0.414	0.120	0.230	0.693	1.000	1000
tau	7.415	4.546	2.080	18.951	1.000	1000
deviance	72.378	5.497	64.016	84.715	1.000	1000

For each parameter, n.eff is a crude measure of effective sample size, and Rhat is the potential scale reduction factor (at convergence, Rhat=1).

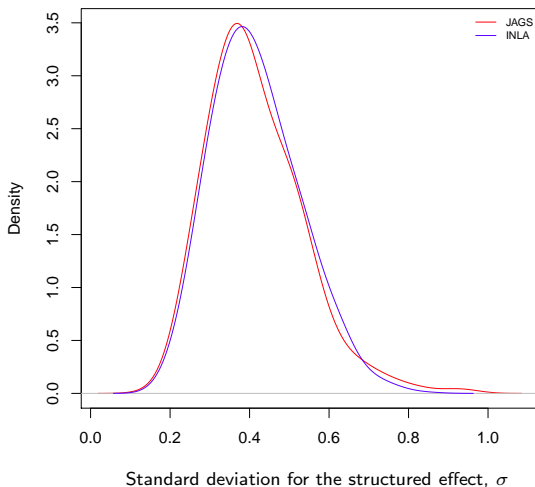
DIC info (using the rule, $pD = \text{var}(\text{deviance})/2$)

$pD = 15.1$ and $DIC = 87.5$

DIC is an estimate of expected predictive error (lower deviance is better).



Posterior distribution for $\sigma = \tau^{-\frac{1}{2}}$



- R-INLA allows to make predictive inference based on the observed model
- Suppose for example that the $(n + 1)$ -th value is not (yet) observed for the response variable y
 - **NB:** for R-INLA, a missing value in the response means no likelihood contribution

- R-INLA allows to make predictive inference based on the observed model
- Suppose for example that the $(n + 1)$ -th value is not (yet) observed for the response variable y
 - **NB:** for R-INLA, a missing value in the response means no likelihood contribution
- We can code this in R, by augmenting the original dataset

```
y[n+1] <- NA
Ntrials[n+1] <- sample(c(80:100),size=1,replace=TRUE)
data2 <- data.frame(y=y,z=1:(n+1),Ntrials=Ntrials)

formula2 = y ~ f(z,model="iid",hyper=list(list(prior="flat")))
m2=inla(formula2,data=data2,
        family="binomial",
        Ntrials=Ntrials,
        control.predictor = list(compute = TRUE))

summary(m2)
```

Time used:

Pre-processing	Running inla	Post-processing	Total
0.0883	0.0285	0.0236	0.1404
(0.2258)	(0.0263)	(0.0744)	(0.3264)

Fixed effects:

	mean	sd	0.025quant	0.5quant	0.975quant	kld
(Intercept)	-0.0021	0.136	-0.272	-0.0021	0.268	0
	(-0.0021)	(0.136)	(-0.272)	(-0.0021)	(0.268)	(0)

Random effects:

Name Model
z IID model

Model hyperparameters:

	mean	sd	0.025quant	0.5quant	0.975quant
Precision for z	7.130	4.087	2.168	6.186	17.599
	(7.130)	(4.087)	(2.168)	(6.168)	(17.599)

Expected number of effective parameters(std dev): 9.494(0.7925)

Number of equivalent replicates : 1.264

Marginal Likelihood: -54.28

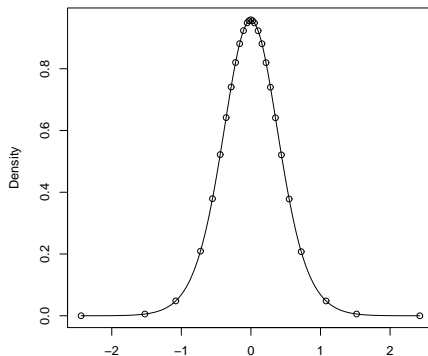
CPO and PIT are computed

Posterior marginals for linear predictor and fitted values computed

- The estimated value for the predictive distribution can be retrieved using the following code

```
pred <- m2$marginals.linear.predictor[[n+1]]  
plot(pred,xlab="",ylab="Density")  
lines(inla.smarginal(pred))
```

which can be used to generate, eg a graph of the predictive density



- It is possible to specify link functions that are different from the default used by R-INLA
- This is done by specifying suitable values for the option `control.family` to the call to `inla`, eg

```
m = inla(formula, data=data, family="binomial", Ntrials=Ntrials,  
        control.predictor=list(compute=TRUE),  
        control.family = list(link = "probit"))
```


- It is possible to specify link functions that are different from the default used by R-INLA
- This is done by specifying suitable values for the option `control.family` to the call to `inla`, eg

```
m = inla(formula, data=data, family="binomial", Ntrials=Ntrials,  
         control.predictor=list(compute=TRUE),  
         control.family = list(link = "probit"))
```

- More details are available on the R-INLA website:
 - <http://www.r-inla.org/models/likelihoods>

- R-INLA has a set of default priors for the different components of the LGM/GMRF
- For example, in a standard hierarchical formulation, R-INLA assumes
 - Unstructured (“fixed”) effects: $\beta \sim \text{Normal}(0, 0.001)$
 - Structured (“random”) effects: $f(z_i) \sim \text{Normal}(0, \tau)$
 $\log \tau \sim \text{logGamma}(1, 0.00005)$
- **NB:** It is possible to see the default settings using the function

```
inla.model.properties(<name>, <section>)
```

- R-INLA has a set of default priors for the different components of the LGM/GMRF
- For example, in a standard hierarchical formulation, R-INLA assumes
 - Unstructured (“fixed”) effects: $\beta \sim \text{Normal}(0, 0.001)$
 - Structured (“random”) effects: $f(z_i) \sim \text{Normal}(0, \tau)$
 $\log \tau \sim \log\text{Gamma}(1, 0.00005)$
- **NB:** It is possible to see the default settings using the function

```
inla.model.properties(<name>, <section>)
```

- However, there is a wealth of possible formulations that the user can specify, especially for the hyperpriors
- More details are available on the R-INLA website:
 - <http://www.r-inla.org/models/likelihoods>
 - <http://www.r-inla.org/models/latent-models>
 - <http://www.r-inla.org/models/priors>

Models for the observed data

Model	Name
Negative Binomial	nbinomial
Poisson	poisson
Binomial	binomial
Clustered Binomial	cbinomial
Gaussian	gaussian
Skew Normal	sn
Laplace	laplace
Student-t	T
Gaussian model for stochastic volatility	stochvol
Student-t model for stochastic volatility	stochvol.t
NIG model for stochastic volatility	stochvol.nig
Zero inflated Poisson	zeroinflated.poisson.x (x=0,1,2)
Zero inflated Binomial	zeroinflated.binomial.x (x=0,1)
Zero inflated negative Binomial	zeroinflated.nbinomial.x (x=0,1,2)
Zero inflated beta binomial (type 2)	zeroinflated.betabinomial.2
Generalised extreme value distribution (GEV)	gev
Beta	beta
Gamma	gamma
Beta-Binomial	betabinomial
Logistic distribution	logistic
Exponential (Survival models)	exponential
Weibull (Survival model)	weibull
LogLogistic (Survival model)	loglogistic
LogNormal (Survival model)	lognormal
Cox model (Survival model)	coxph

Models for the GMRF

Model	Name
Independent random variables	iid
Linear	linear
Random walk of order 1	rw1
Random walk of order 2	rw2
Continuous random walk of order 2	crw2
Model for seasonal variation	seasonal
Model for spatial effect	besag
Model for spatial effect	besagproper
Model for weighted spatial effects	besag2
Model for spatial effect + random effect	bym
Autoregressive model of order 1	ar1
Autoregressive model of order p	ar
The Ornstein-Uhlenbeck process	ou
User defined structure matrix, type 0	generic0
User defined structure matrix, type1	generic1
User defined structure matrix, type2	generic2
Model for correlated effects with Wishart prior (dimension 1, 2, 3, 4 and 5).	iid1d, iid2d, iid3d, iid4d, iid5d
(Quite) general latent model	z
Random walk of 2nd order on a lattice	rw2d
Gaussian field with Matern covariance function	matern2d
Classical measurement error model	mec
Berkson measurement error model	meb

Models for the hyper-parameters

Model	Name
Normal distribution	normal, gaussian
Log-gamma distribution	loggamma
Improper flat prior	flat
Truncated Normal distribution	logtnormal, logtgaussian
Improper flat prior on the log scale	logflat
Improper flat prior on the 1/ log scale	logiflat
Wishart prior	wishart
Beta for correlations	betacorrelation
Logit of a Beta	logitbeta
Define your own prior	expression:

- Hyper-parameters (eg correlation coefficients ρ or precisions τ) are represented internally using a suitable transformation, eg

$$\psi_1 = \log(\tau)$$

or

$$\psi_2 = \log\left(\frac{1 + \rho}{1 - \rho}\right)$$

to improve symmetry and approximate Normality

- Hyper-parameters (eg correlation coefficients ρ or precisions τ) are represented internally using a suitable transformation, eg

$$\psi_1 = \log(\tau)$$

or

$$\psi_2 = \log\left(\frac{1 + \rho}{1 - \rho}\right)$$

to improve symmetry and approximate Normality

- Initial values are given on the internal scale
- Priors are also defined on the internal scale
- So, when specifying custom values, care is needed!

- Current work on a more general class of priors — “penalised complexity priors” (see <http://arxiv.org/pdf/1403.4630v1.pdf>)

Consider the model

$$\begin{aligned}y_i \mid \theta_i, \sigma^2 &\sim \text{Normal}(\theta_i, \sigma^2) \\ \theta_i &= \alpha + \beta x_i \\ \alpha, \beta &\stackrel{iid}{\sim} \text{Normal}(0, 0.001) \\ \log \tau = -\log \sigma^2 &\sim \text{logGamma}(1, 0.01)\end{aligned}$$

```
n=100
a = 1; b = 1
x = rnorm(n)
eta = a + b*x
tau = 100
scale = exp(rnorm(n))
prec = scale*tau
y = rnorm(n, mean = eta, sd = 1/sqrt(prec))
data = list(y=y, x=x)
formula = y ~ 1 + x
result = inla(formula, family = "gaussian", data = data,
              control.family = list(hyper = list(
                prec = list(prior = "loggamma", param = c(1,0.01), initial = 2))),
              scale=scale, keep=TRUE)
summary(result)
```

Time used:

Pre-processing	Running inla	Post-processing	Total
0.0776	0.0828	0.0189	0.1793

Fixed effects:

	mean	sd	0.025quant	0.5quant	0.975quant	kld
(Intercept)	1.0013	0.0074	0.9868	1.0013	1.0158	0
x	0.9936	0.0075	0.9788	0.9936	1.0083	0

The model has no random effects

Model hyperparameters:

	mean	sd	0.025quant	0.5quant	0.975quant
Precision for the Gaussian observations	108.00	15.34	80.60	107.09	140.74

Expected number of effective parameters(std dev): 2.298(0.0335)

Number of equivalent replicates : 43.52

Marginal Likelihood: 83.86

CPO and PIT are computed

Consider the model

$$\begin{aligned}y_i \mid \mu, \sigma^2 &\sim \text{Normal}(\mu, \sigma^2) \\ \mu &\sim \text{Normal}(0, 0.001) \\ \log \tau = -\log \sigma^2 &\sim \text{Normal}(0, 1)\end{aligned}$$

```
n = 10
y = rnorm(n)
formula = y ~ 1
result = inla(formula, data = data.frame(y),
              control.family = list(hyper = list(
                prec = list(prior = "normal", param = c(0,1))))
)
summary(result)
```

Consider the model

$$\begin{aligned}y_i \mid \mu, \sigma^2 &\sim \text{Normal}(\mu, \sigma^2) \\ \mu &\sim \text{Normal}(0, 0.001) \\ \log \tau = -\log \sigma^2 &\sim \text{Normal}(0, 1)\end{aligned}$$

```
n = 10
y = rnorm(n)
formula = y ~ 1
result = inla(formula, data = data.frame(y),
              control.family = list(hyper = list(
                prec = list(prior = "normal", param = c(0,1))))
)
summary(result)
```

- **NB:** INLA thinks in terms of LGMs and GMRFs
- Thus, the common mean for all the observations is specified in terms of a regression!

Time used:

Pre-processing	Running inla	Post-processing	Total
0.0740	0.0214	0.0221	0.1175

Fixed effects:

	mean	sd	0.025quant	0.5quant	0.975quant	kld
(Intercept)	-0.3853	0.4077	-1.1939	-0.3853	0.4237	0

The model has no random effects

Model hyperparameters:

	mean	sd	0.025quant	0.5quant	0.975quant
Precision for the Gaussian observations	0.6512	0.268	0.2590	0.6089	1.2919

Expected number of effective parameters(std dev): 1.00(0.00)

Number of equivalent replicates : 9.999

Marginal Likelihood: -17.30

CPO and PIT are computed

Running the model in JAGS

```
model {  
  for (i in 1:n) {  
    y[i] ~ dnorm(mu,tau)  
  }  
  mu ~ dnorm(0,0.001)  
  log.tau ~ dnorm(0,1)  
  tau <- exp(log.tau)  
}
```

produces similar results

Inference for Bugs model at "modelHyperPriorNormal.txt", fit using jags,
2 chains, each with 1e+05 iterations (first 9500 discarded), n.thin = 181
n.sims = 1000 iterations saved

	mu.vect	sd.vect	2.5%	97.5%	Rhat	n.eff
mu	-0.384	0.447	-1.293	0.555	1.000	1000
tau	0.642	0.258	0.233	1.240	1.006	1000
deviance	34.507	1.930	32.645	39.897	1.002	650

For each parameter, n.eff is a crude measure of effective sample size,
and Rhat is the potential scale reduction factor (at convergence, Rhat=1).

DIC info (using the rule, $pD = \text{var}(\text{deviance})/2$)

$pD = 1.9$ and $DIC = 36.4$

DIC is an estimate of expected predictive error (lower deviance is better).

- We can also assume different priors for the unstructured (“fixed”) effects, eg suppose we want to fit the model

$$\begin{aligned}y_i \mid \mu, \sigma^2 &\sim \text{Normal}(\mu, \sigma^2) \\ \mu &\sim \text{Normal}(10, 4) \\ \log \tau = -\log \sigma^2 &\sim \text{Normal}(0, 1)\end{aligned}$$

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- This can be done by using the option `control.fixed`, eg

```
result = inla(formula, data = data.frame(y),
              control.family = list(hyper = list(
                prec = list(prior = "normal", param = c(0, 1))))
              control.fixed=list(
                mean.intercept=10, prec.intercept=4)
              )
```


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              control.fixed=list(
                mean.intercept=10, prec.intercept=4)
              )
```

- **NB:** If the model contains fixed effects for some covariates, non-default priors can be included using the option

```
control.fixed=list(mean=list(value), prec=list(value))
```

Time used:

Pre-processing	Running inla	Post-processing	Total
0.0747	0.0311	0.0164	0.1222

Fixed effects:

	mean	sd	0.025quant	0.5quant	0.975quant	kld
(Intercept)	9.5074	0.502	8.5249	9.5067	10.4935	0
	-0.3853	0.407	-1.1939	-0.3853	0.4237	0

The model has no random effects

Model hyperparameters:

	mean	sd	0.025quant	0.5quant	0.975quant
Precision for the Gaussian observations	0.0218	0.007	0.0105	0.0208	0.0391
	0.6512	0.268	0.2590	0.6089	1.2919

Expected number of effective parameters(std dev): 0.0521(0.0129)
1.0000(0.0000)

Number of equivalent replicates : 192.05
9.9999

Marginal Likelihood: 153.84
-17.30

CPO and PIT are computed

- As mentioned earlier, for computational reasons, by default INLA uses a relatively rough grid to estimate the marginal posterior for the hyperparameters $p(\boldsymbol{\psi} | \boldsymbol{y})$
- This is generally good enough, but the procedure can be refined

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- This is generally good enough, but the procedure can be refined
- After the model has been estimated using the standard procedure, it is possible to increase precision in the estimation by re-fitting it using the command

```
inla.hyperpar(m, options)
```

- This modifies the estimation for the hyperparameters and (potentially, but not necessarily!) that for the parameters

- Consider the classic model for seizure counts in a RCT of anti-conversant therapy in epilepsy (“Epilepsy” in the BUGS manual)
- The data are as follows

Patient	Visit 1	Visit 2	Visit 3	Visit 4	Trt	Base	Age
1	5	3	3	3	0	11	31
2	3	5	3	3	0	11	30
...
59	1	4	3	2	1	12	37

- We replicate the model presented in the BUGS manual, which uses slightly modified version of the covariates

We model

$$\begin{aligned}y_{jk} &\sim \text{Poisson}(\mu_{jk}) \\ \log(\mu_{jk}) &= \alpha_0 + \alpha_1 \log(B_j/4) + \alpha_2 Trt_j + \\ &\quad \alpha_3 Trt_j \times \log(B_j/4) + \alpha_4 \log(Age_j) + \\ &\quad \alpha_5 V4_k + u_j + v_{jk} \\ \alpha_0, \dots, \alpha_5 &\stackrel{iid}{\sim} \text{Normal}(0, \tau_\alpha), \quad \tau_\alpha \text{ known} \\ u_j &\sim \text{Normal}(0, \tau_u), \quad \tau_u \sim \text{Gamma}(a_u, b_u) \\ v_{jk} &\sim \text{Normal}(0, \tau_v), \quad \tau_v \sim \text{Gamma}(a_v, b_v)\end{aligned}$$

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 &\quad \alpha_3 \text{Trt}_j \times \log(B_j/4) + \alpha_4 \log(\text{Age}_j) + \\
 &\quad \alpha_5 V_{4k} + u_j + v_{jk} \\
 \alpha_0, \dots, \alpha_5 &\stackrel{iid}{\sim} \text{Normal}(0, \tau_\alpha), \quad \tau_\alpha \text{ known} \\
 u_j &\sim \text{Normal}(0, \tau_u), \quad \tau_u \sim \text{Gamma}(a_u, b_u) \\
 v_{jk} &\sim \text{Normal}(0, \tau_v), \quad \tau_v \sim \text{Gamma}(a_v, b_v)
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$\alpha = (\alpha_0, \dots, \alpha_5)$ indicates a set of “fixed” effects for the relevant (re-scaled) covariates

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 v_{jk} &\sim \text{Normal}(0, \tau_v), \quad \tau_v \sim \text{Gamma}(a_v, b_v)
 \end{aligned}$$

$\alpha = (\alpha_0, \dots, \alpha_5)$ indicates a set of “fixed” effects for the relevant (re-scaled) covariates

u_j is an individual “random” effect

v_{jk} is a subject by visit “random” effect, which accounts for extra-Poisson variability

```
data(Epil)
head(Epil,n=3)
  y Trt Base Age V4 rand Ind
1 5  0  11  31  0   1   1
2 3  0  11  31  0   2   1
3 3  0  11  31  0   3   1

formula <- y ~ log(Base/4) + Trt +
  I(Trt * log(Base/4)) + log(Age) + V4 +
  f(Ind, model = "iid") + f(rand, model="iid")

m <- inla(formula, family="poisson", data = Epil)
```

- **NB:** The variable `Ind` indicates the individual random effect u_j , while the variable `rand` is used to model the subject by visit random effect v_{jk}
- Interactions can be indicated in the R formula using the notation

`I(var1 * var2)`

- The model assumes that the two structured effects are independent. This can be relaxed and a joint model can be used instead

Pre-processing	Running inla	Post-processing	Total
0.3672	0.2780	0.1276	0.7728

Fixed effects:

	mean	sd	0.025quant	0.5quant	0.975quant	kld
(Intercept)	-1.3877	1.2107	-3.7621	-1.3913	1.0080	0.0055
log(Base/4)	0.8795	0.1346	0.6144	0.8795	1.1447	0.0127
Trt	-0.9524	0.4092	-1.7605	-0.9513	-0.1498	0.0021
I(Trt * log(Base/4))	0.3506	0.2081	-0.0586	0.3504	0.7611	0.0011
log(Age)	0.4830	0.3555	-0.2206	0.4843	1.1798	0.0007
V4	-0.1032	0.0853	-0.2705	-0.1032	0.0646	0.0003

Random effects:

Name	Model
Ind	IID model
rand	IID model

Model hyperparameters:

	mean	sd	0.025quant	0.5quant	0.975quant
Precision for Ind	4.635	1.343	2.591	4.436	7.808
Precision for rand	8.566	2.115	5.206	8.298	13.458

Expected number of effective parameters(std dev): 118.97(8.586)

Number of equivalent replicates : 1.984

Marginal Likelihood: -670.55

Pre-processing	Running inla	Post-processing	Total
0.3672	0.2780	0.1276	0.7728

(MCMC: approximately 30 mins)

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 - Documentation and examples is more extensive for standard MCMC models
- Nevertheless, INLA proves to be a very flexible tool, which is able to fit a very wide range of models
 - Generalised linear (mixed) models
 - Log-Gaussian Cox processes
 - Survival analysis
 - Spline smoothing
 - Spatio-temporal models
- The INLA setup can be highly specialised (choice of data models, priors and hyperpriors) although this is a bit less intuitive than (most) MCMC models

Thank you!